

Solution of Cauchy's Problem By Using Spline Interpolation

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Abstract

The aim of this paper is to obtain an approximate solution of Cauchy's problem of the second order by using deficient sextic spline which interpolates the lacunary data $(0,1,4)$. Also, we studied the convergence for the approximate solution to the exact solution.

Introduction

Let us consider the Cauchy's initial value problem

$$y'' = f(x, y, y'), \quad x \in [0,1], \quad y(0) = y_0, \quad y'(0) = y'_0 \quad (1.1)$$

Here we assume that $f(x, y, y') \in C^r[0,1]$,

$r \geq 0$, { where $C^r[0,1]$ is the set of all continuously differentiable functions r -times over $[0,1]$ } and satisfies the Lipschitz condition

$$|f^{(q)}(x, y_1, y'_1) - f^{(q)}(x, y_2, y'_2)| \leq L(|y_1 - y_2| + |y'_1 - y'_2|),$$

$q = 0, 1, \dots, r$ for all $x \in [0,1]$, where L is the

Lipschitz constant and y_1, y_2, y'_1 and y'_2 are real valued functions. This condition ensures the existence of unique solution of the problem (1.1) [5]. Siddiqi and Akam [6] used quintic spline to find an approximation solution of fourth order boundary-value problems.

In the last several years various authors have used spline functions for finding an approximate solution of initial value problems including (1.1) [1,2,3, and 5], that the spline functions of full continuity do not converge to exact solution for arbitrary degrees of the spline (see for example [2] and [3]). For this reason the continuity conditions are relaxed. Saeed [3] used the same idea for finding approximate solution of (1.1) but for the lacunary data $(0,2,5)$. In this paper we consider the same problem but for the lacunary data $(0,1,4)$.

Definition of the approximate values $\bar{Y}_k^{(q)}$

Let $x_k = \frac{k}{m}$; $h = \frac{1}{m}$; $w_m(h) = \max_{x \in [0,1]} \{ |y^{(r+2)}(x) - y^{(r+2)}(x_k)| \}$, $k=0,1,\dots,m$

$\bar{Y}_k^{(q)} : \bar{y}_0^{(q)}, \bar{y}_1^{(q)}, \dots, \bar{y}_m^{(q)}$; $q=0,1,\dots,r+2$, be the approximate values which are an approximate to the exact values

$Y^{(q)} : y_0^{(q)}, y_1^{(q)}, \dots, y_m^{(q)}$; $q=0,1,\dots,r+2$. By using these approximate values we construct a spline function $\bar{S}_\Delta(x)$ which interpolates to the set \bar{Y} on the mesh Δ and approximate the solution $y(x)$ of

(1.1). The set $\bar{Y}^{(q)}$ is $\bar{y}_0 = y_0, \bar{y}'_0 = y'_0, \bar{y}_0^{(2+q)} = f^{(q)}(x_0, y(x_0), y'(x_0))$; $q=0,1,\dots,r$.

$$\bar{y}_k = \bar{y}_0 - h \bar{y}'_0 - \int_0^x \int_0^t f(u, v_k(u), v'_k(u)) du dt$$

$$\bar{y}'_k = \bar{y}'_0 + \int_0^x f(t, v_k(t), v'_k(t)) dt$$

$$\bar{y}_k^{(2+q)} = f^{(q)}(x_{k+1}, \bar{y}_{k+1}, \bar{y}'_{k+1}),$$

$$q=0,1,\dots,r, k=0,1,\dots,m-1,$$

$$v'_k(x) = y'_k + \int_0^x f(t, v(t), v'(t)) dt \quad , \quad \text{and for}$$

$$x_k \leq x \leq x_{k+1}; k=0,1,\dots,m-1.$$

$$v_k(x) = \sum_{j=0}^{q-1} \bar{y}_k^{(j)} \frac{(x-x_k)^j}{j!} \quad \text{and}$$

$$v'_k(x) = \sum_{j=0}^{q-1} \bar{y}_k^{(j+1)} \frac{(x-x_k)^j}{j!}$$

The error of the approximate values $\bar{y}_k^{(q)}$ are estimated by the inequality (1.3) in [1] which is $|\bar{y}_k^{(q)} - \bar{y}_k^{(q)}| \leq c_j h^{m+2-j} w_{m+2}(h)$, where $k=0,1,\dots,m-1$ and $j=0,1,\dots,r+2$, see [1, Lemma 2.2.1 and 2.2.3] where c_j 's denote different constants independent of h .

3. The spline function $\bar{S}_\Delta(x)$

Let $\Delta : x_0 < x_1 < \dots < x_{m-1} < x_m = 1$ be the uniform partition of the interval $[0,1]$ with $x_k = \frac{k}{m}, k=0,1,\dots,m$. We denote by $S_p(6,3,m)$ the class of splines $\bar{S}_\Delta(x)$ such that $\bar{S}_\Delta(x) \in C^3[0,1]$ and $\bar{S}_\Delta(x)$ is polynomial of degree six in $[x_0, x_1]$ and $[x_{m-1}, x_m]$ and of degree five in each subintervals $[x_k, x_{k+1}], k=1,2,\dots,m-2$.

Suppose that $\bar{Y}_k^{(q)}, q=0,1,\dots,5$ and $k=0,1,\dots,m$, be given real numbers. Using these approximate values, we construct a unique lacunary spline function $\bar{S}_\Delta(x)$ of the type $(0,1,4)$ which satisfies the following conditions [4]:

$$\left. \begin{aligned} \bar{S}_\Delta(x_k) &= \bar{y}_k \\ \bar{S}_\Delta^{(q)}(x_k) &= \bar{y}_k^{(q)} \text{ where } q=1,4 \text{ and } k=0,1,\dots,m \\ \bar{S}'_\Delta(x_0) &= \bar{y}'_0 \text{ and } \bar{S}'_\Delta(x_m) = \bar{y}'_m \end{aligned} \right\} \dots (2.1)$$

The existence and uniqueness of above spline function have been shown in [4], we have

$$\bar{S}_k(x) = \begin{cases} \bar{S}_0(x), & \text{when } x \in [x_0, x_1] \\ \bar{S}_k(x), & \text{when } x \in [x_k, x_{k+1}], k=1, \dots, m-2 \\ \bar{S}_{m-1}(x), & \text{when } x \in [x_{m-1}, x_m] \end{cases}$$

Where

$$\bar{S}_0(x) = \bar{y}_0 - \bar{y}'_0(x-x_0) - \bar{y}''_0 \frac{(x-x_0)^2}{2} + \bar{a}_{0,3}h^3 + \bar{y}'''_0 \frac{(x-x_0)^3}{6!} - \bar{a}_{1,3}h^3 - \bar{a}_{2,3}h^3, \dots (2.2)$$

$$\bar{S}_k(x) = \bar{y}_k + \bar{y}'_k(x-x_k) - \bar{a}_{k,2}h^2 + \bar{a}_{k,3}h^3 + \bar{y}'''_k \frac{(x-x_k)^3}{4!} + \bar{a}_{k,5}h^5, \dots (2.3)$$

$$\bar{S}_{m-1}(x) = \bar{y}_{m-1} + \bar{y}'_{m-1}(x-x_{m-1}) + \bar{y}''_{m-1} \frac{(x-x_{m-1})^2}{2} + \bar{a}_{m-1,3}h^3 + \bar{y}'''_{m-1} \frac{(x-x_{m-1})^3}{4!} + \bar{a}_{m-1,5}h^5 + \bar{a}_{m-1,6}h^6, \dots (2.4)$$

Here

$$\bar{a}_{0,3} = \frac{1}{6h^3} \{18(\bar{y}'_1 - \bar{y}'_0) - (14\bar{y}''_0 + 4\bar{y}''_1 + 5h^2\bar{y}'''_0)\} + \frac{h}{360}(\bar{y}'''_1 - 6\bar{y}'''_0)$$

$$\bar{a}_{k,3} = -\frac{1}{h^3} \{3(\bar{y}'_1 - \bar{y}'_0) - \frac{1}{2}(4h\bar{y}''_0 + 2h\bar{y}''_1 + h^2\bar{y}'''_0)\} - \frac{1}{120h}(\bar{y}'''_1 + 4\bar{y}'''_0)$$

$$\bar{a}_{0,5} = \frac{1}{3h^5} \{3(\bar{y}'_1 - \bar{y}'_0) - \frac{1}{2}(4h\bar{y}''_0 + 2h\bar{y}''_1 + h^2\bar{y}'''_0)\} + \frac{1}{360h^2}(2\bar{y}'''_1 + 3\bar{y}'''_0)$$

$$\bar{a}_{k,2} = \frac{1}{h^2} \{3(\bar{y}'_{k+1} - \bar{y}'_k) - 2h\bar{y}''_k - h\bar{y}''_{k+1}\} + \frac{h^2}{120}(2\bar{y}'''_{k+1} + 3\bar{y}'''_k)$$

$$\bar{a}_{k,3} = \frac{1}{h^3} \{-2(\bar{y}'_{k+1} - \bar{y}'_k) + h\bar{y}''_k + h\bar{y}''_{k+1}\} - \frac{h}{120}(3\bar{y}'''_{k+1} + 7\bar{y}'''_k)$$

$$\bar{a}_{k,5} = \frac{1}{120h}(\bar{y}'''_{k+1} - \bar{y}'''_k)$$

Convergence of a spline function

In this section, we find the order of convergence for spline function $\bar{S}_k(x)$

given in section two to the exact solution of problem (1.1). We also prove that it satisfies the differential equation in (1.1) as $m \rightarrow \infty$, let $\bar{S}_k(x)$ be the spline function corresponding to the

approximate values $\bar{y}_k, k=0,1,\dots,m$ and let $S_k(x)$ be the spline function corresponding to the exact values $y_k, k=0,1,\dots,m$ of problem (1.1). Then we have the following theorems

Theorem 1 The following estimates are valid

$$(i) \quad |S_k^{(q)} - \bar{S}_k^{(q)}| \leq B_q h^q w_k(h), q=0,1,\dots,5; k=0,1,\dots,m-1$$

Where B_q denote different constants

independent of h .

$$(ii) \quad |y^{(q)}(x) - S_k^{(q)}(x)| \leq E_q h^q w_k(h); q=0,1,\dots,5$$

Where $y(x)$ is the exact solution of (1.1) and E_q denote different constants independent of h

Proof of the theorem 1 (i): we have owing to (2.2)

$$S_0(x) - \bar{S}_0(x) = h^3(a_{0,3} - \bar{a}_{0,3}) + h^5(a_{0,5} - \bar{a}_{0,5}) + h^6(a_{0,6} - \bar{a}_{0,6}),$$

where

$$a_{0,3} - \bar{a}_{0,3} = 3h^3(y'_1 - \bar{y}'_1) + \frac{2}{3}h^2(y''_1 - \bar{y}''_1) + \frac{h}{360}(y'''_1 - \bar{y}'''_1)$$

Using (1.3) we have

$$|a_{0,3} - \bar{a}_{0,3}| \leq \frac{1}{360}(120c_0 + 240c_1 + c_2)h^4 w_0(h) \text{ where } = I_0 h^4 w_0(h)$$

$I_0 = \frac{1}{360}(120c_0 + 240c_1 + c_2)$ and c_0, c_1 and c_2 are constants independent of h .

Similarly

$$|a_{0,5} - \bar{a}_{0,5}| \leq \frac{1}{120}(360c_0 + 120c_1 + c_2)h^2 w_0(h) \text{ where } = I_1 h^2 w_0(h)$$

$$I_1 = \frac{1}{120}(360c_0 + 120c_1 + c_2)$$

$$\text{and } |a_{0,6} - \bar{a}_{0,6}| \leq \frac{1}{180}(180c_0 + 60c_1 + c_2)h w_0(h) = I_2 h w_0(h)$$

where

$$I_2 = \frac{1}{180}(180c_0 + 60c_1 + c_2)$$

Hence

$$|S_0(x) - \bar{S}_0(x)| = h^3 |a_{0,3} - \bar{a}_{0,3}| + h^5 |a_{0,5} - \bar{a}_{0,5}| + h^6 |a_{0,6} - \bar{a}_{0,6}| \leq I h^3 w_0(h)$$

where $I = I_0 + I_1 + I_2$,

and by successive differentiations

$$|S_0^{(q)}(x) - \bar{S}_0^{(q)}(x)| \leq b_q h^q w_0(h); q=0,1,\dots,5$$

This proves (3.1) for $k=0$ and $x \in [x_0, x_1]$. Further, owing to (2.3)

$$S_k(x) - \bar{S}_k(x) = (y_k - \bar{y}_k) + (y'_k - \bar{y}'_k)(x-x_k) + h^2(a_{k,2} - \bar{a}_{k,2}) + h^3(a_{k,3} - \bar{a}_{k,3}) + (y_k^{(3)} - \bar{y}_k^{(3)}) \frac{(x-x_k)^3}{4} + h^5(a_{k,5} - \bar{a}_{k,5})$$

We have owing to (1.3) we get

$$a_{k,2} - \bar{a}_{k,2} = h^2 \{3(y'_{k+1} - y'_k) + 2h \{y''_k - h y'''_{k+1}\} + \frac{h^2}{120} (2y^{(4)}_{k-1} + 3y^{(4)}_k) - h^2 \{3(\bar{y}'_{k+1} - y'_k) + 2h \{y''_k - h y'''_{k+1}\} - \frac{h^2}{120} (2\bar{y}^{(4)}_{k-1} + 3\bar{y}^{(4)}_k)\}$$

Now

$$|a_{k,2} - \bar{a}_{k,2}| \leq \frac{1}{25} (7k_1 + k_2) h^3 w_3(h) - L_1 h^3 w_3(h)$$

where $L_1 = \frac{1}{25} (75k_1 + k_2)$.

And k_1 and k_2 are constants independent of h

Similarly

$$|a_{k,1} - \bar{a}_{k,1}| < L_2 h^4 w_4(h)$$

$$\text{and } |a_{k,3} - \bar{a}_{k,3}| \leq L_3 h^2 w_3(h)$$

where L_2, L_3 and L_4 are constants independent of h .

Hence $|S_3(x) - \bar{S}_3(x)| < dh^2 w_3(h)$, where $d = L_1 + L_2 + L_3$

and by successive differentiation we get

$$|S_q^{(j)}(x) - \bar{S}_q^{(j)}(x)| \leq d_j h^{2-j} w_q(h), \quad q = 0, 1, \dots, 5.$$

This proves (i) for $k=1, 2, \dots, m-2$.

We can repeat the same manner in above for $k=m-1$. Hence the proof of theorem 1(i) is complete.

Proof of the theorem 1(ii):

$$|y^{(q)}(x) - \bar{S}_q^{(q)}(x)| < |y^{(q)}(x) - S_q^{(q)}(x) - [S_q^{(q)}(x) - \bar{S}_q^{(q)}(x)]|$$

From [4, theorem 3.1] the following estimates are valid

$$|S_q^{(q)}(x) - y^{(q)}(x)| \leq k_q h^{2-q} w_q(h), \quad q = 0, 1, \dots, 5.$$

Using this estimate and estimate in theorem 1(i) we have

$$|y^{(q)}(x) - \bar{S}_q^{(q)}(x)| < k_q h^{2-q} w_q(h) + B_q h^{2-q} w_q(h) = (k_q + h^2 B_q) h^{2-q} w_q(h) = E_q h^{2-q} w_q(h);$$

$q=0, 1, \dots, 5$, where $E_q = k_q + h^2 B_q$

Which proves (ii).

The above theorem give error estimate between the approximating spline $S_q(x)$ and the exact solution

of (1.1), also for $h \rightarrow \frac{1}{m}$ the following theorem

shows that $S_q(x)$ satisfies the differential equation (1.1) as $m \rightarrow \infty$.

Theorem 2: The following estimates is valid

$$|\bar{S}_q^{(q)}(x) - f(x, \bar{S}_q(x), \bar{S}'_q(x))| \leq R h^3 w_q(h)$$

where R is constant independent of h .

Proof: We have

$$\bar{S}_q^{(q)}(x) - f(x, \bar{S}_q(x), \bar{S}'_q(x)) = \bar{S}_q^{(q)}(x) - y^{(q)}(x) + y^{(q)}(x) - f(x, \bar{S}_q(x), \bar{S}'_q(x)) = [\bar{S}_q^{(q)}(x) - y^{(q)}(x)] + [y^{(q)}(x) - f(x, \bar{S}_q(x), \bar{S}'_q(x))].$$

Therefore, owing to the Lipschitz condition

$$|\bar{S}_q^{(q)}(x) - f(x, \bar{S}_q(x), \bar{S}'_q(x))| \leq |\bar{S}_q^{(q)}(x) - y^{(q)}(x)| + L(|y(x) - \bar{S}_q(x)| + |y'(x) - \bar{S}'_q(x)|).$$

we get the proof of the theorem by using theorem 1(ii) for $q=0, 1, 2$.

Conclusion

In this work, with [2],[3] and [5] we conclude that the type of the lacunary data has no any role in deciding the order of convergence, but the degree of the spline function has to plays a very important role in deciding the rate of convergence. For this reason, to find a best approximate solution for Cauchy's problem, we must use greatest possible degree for spline function to obtain best accuracy.

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الخلاصة

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